Technical Overview of the 4pi Calibration System

The 4pi Group

4π Group

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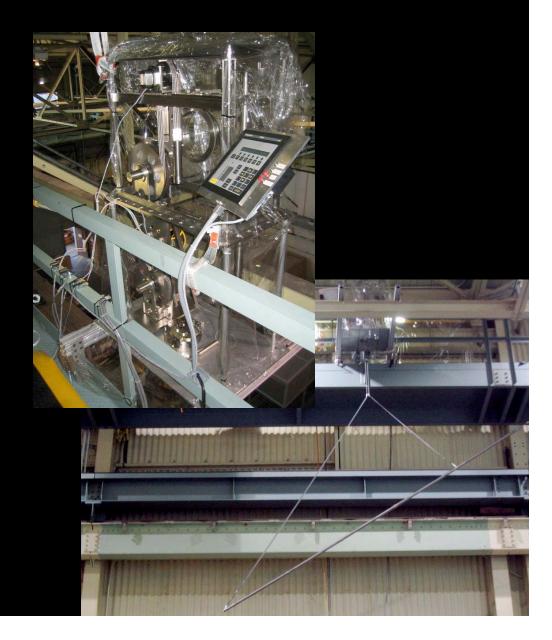
L. Winslow

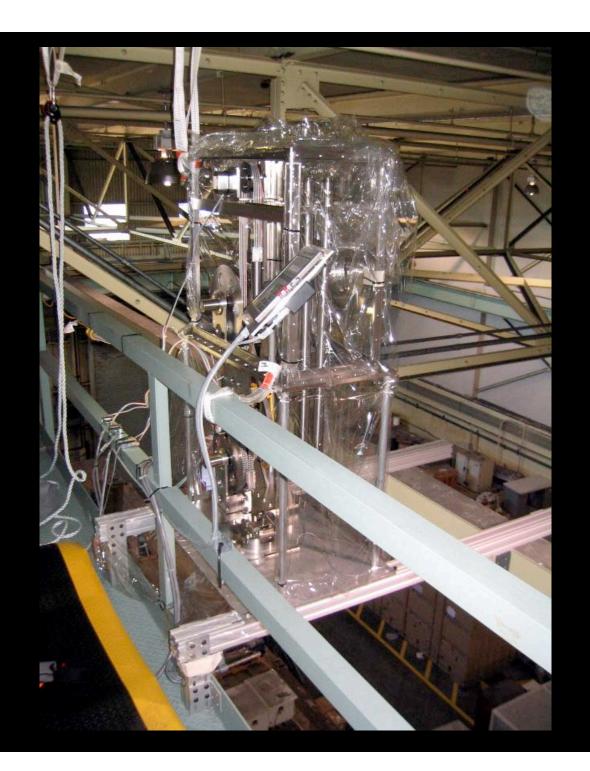
http://kmheeger.lbl.gov/kamland/4pi/

March 1, 2003 The "coat hanger" idea



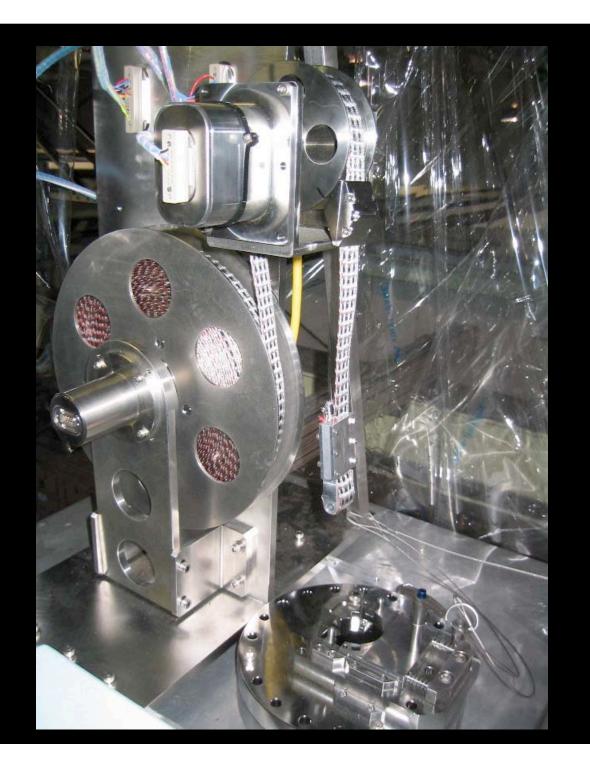
September 16, 2004 Full test of deployment system

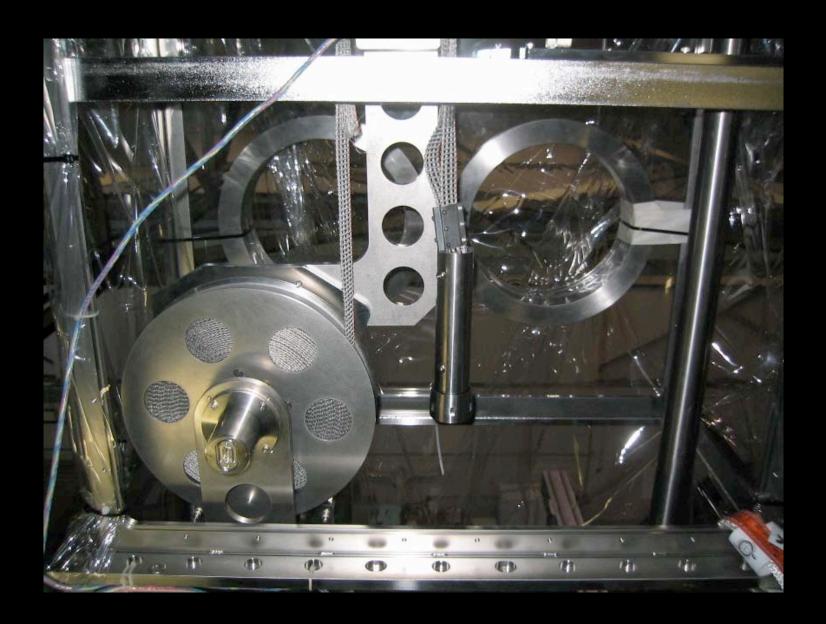


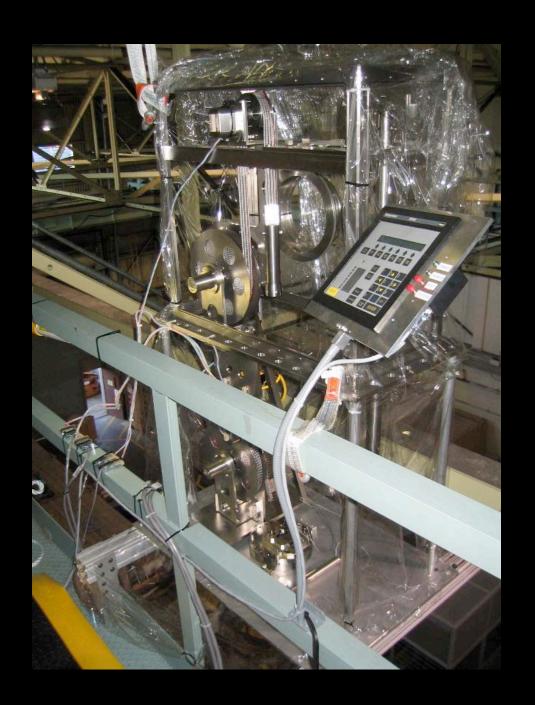








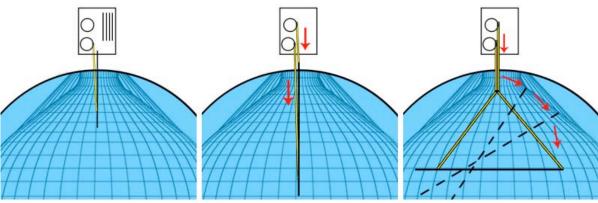








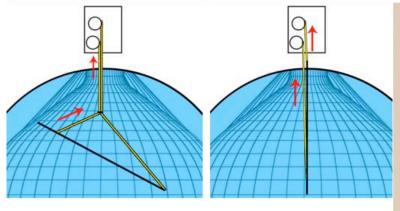
Calibration throughout entire detector volume



Fiducial volume:

R < 5 m

$$\Delta R_{FV} = 5 \text{ cm}$$
 $\rightarrow \Delta V = 3\%$



Position Dependence of Detector Response

 $\begin{array}{ll} \text{Event energy} & \text{E}(r,\theta,\phi) \\ \text{Vertex reconstruction} & \text{R}_{\text{fit}}(r,\theta,\phi) \end{array}$

control cables

fiducial volume
R<5-m

Off-Axis Calibration System

I. Hardware

Glovebox System and Deployment Hardware

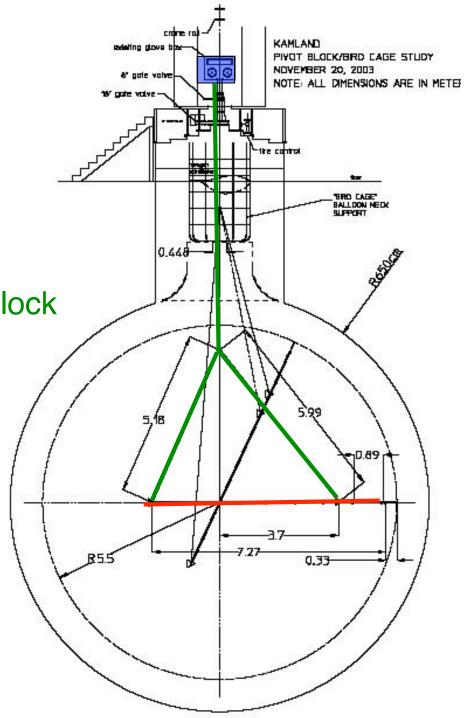
Control Cable + Pivot Block

Calibration Pole

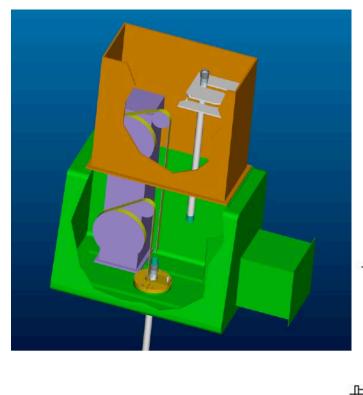
II. System Control Software

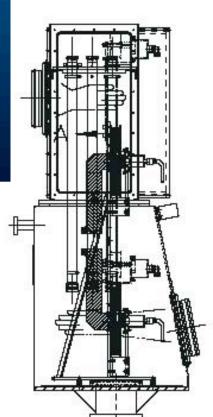
→ Fred Gray

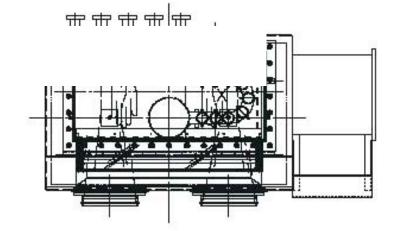
III. Position Reconstruction

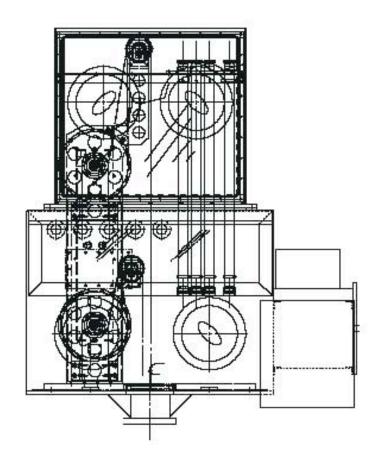


Glovebox System and Deployment Hardware



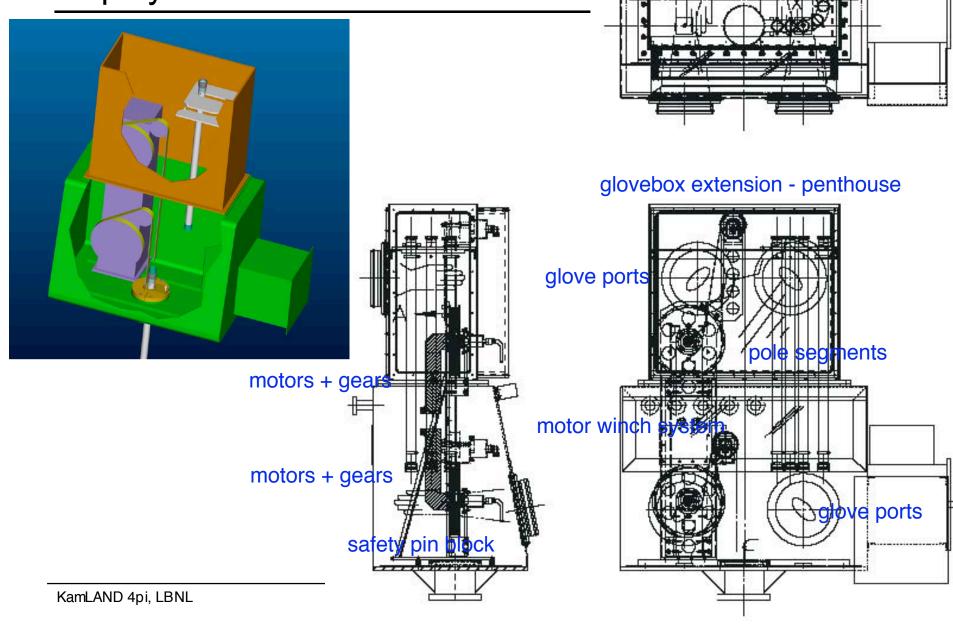




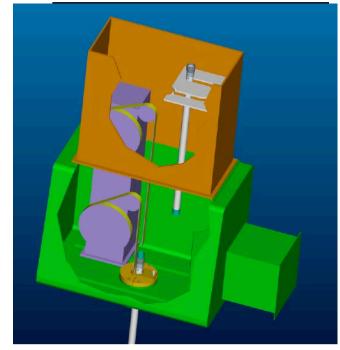


KamLAND 4pi, LBNL

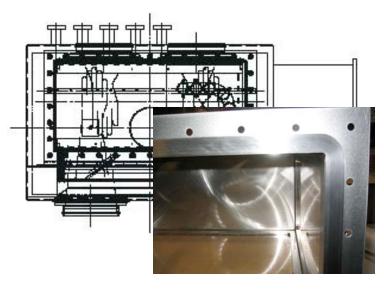
Glovebox System and Deployment Hardware



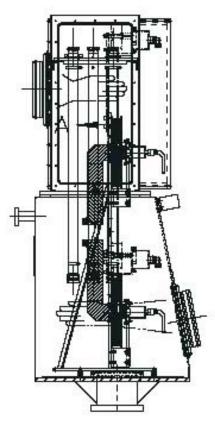
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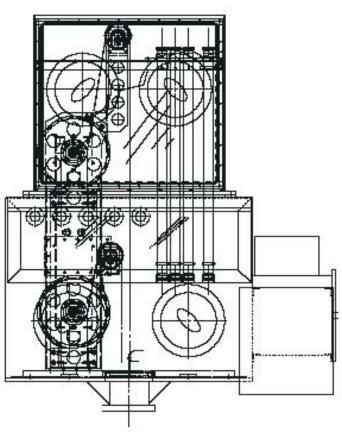






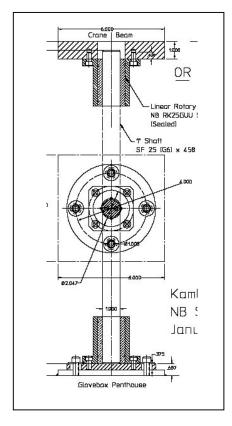




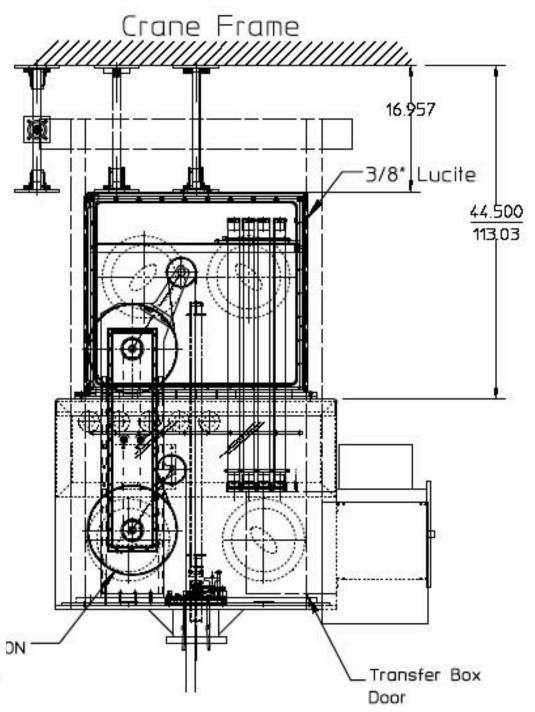


KamLAND 4pi, LBNL

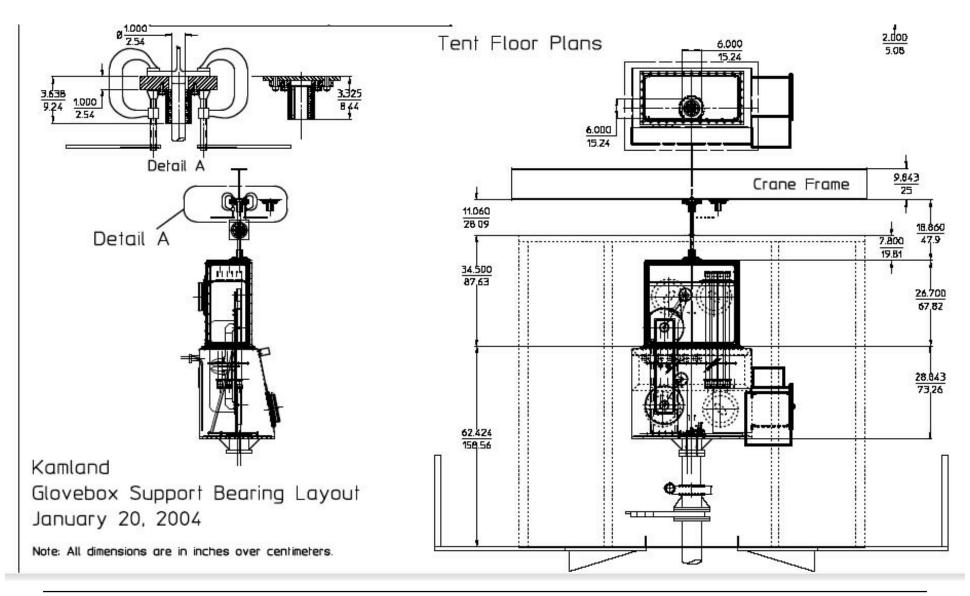
Glovebox Axial Support



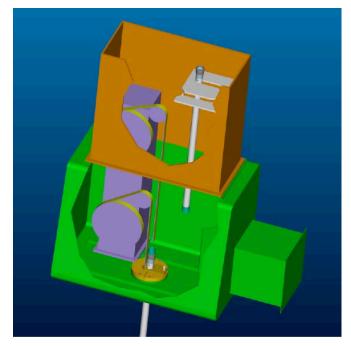
- provides axial stability
- allows system to rotate
- avoids future problems with rotary stage

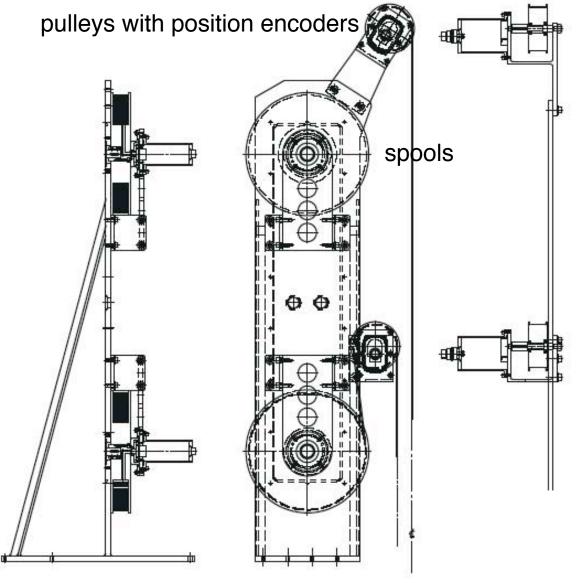


Glovebox Axial Support

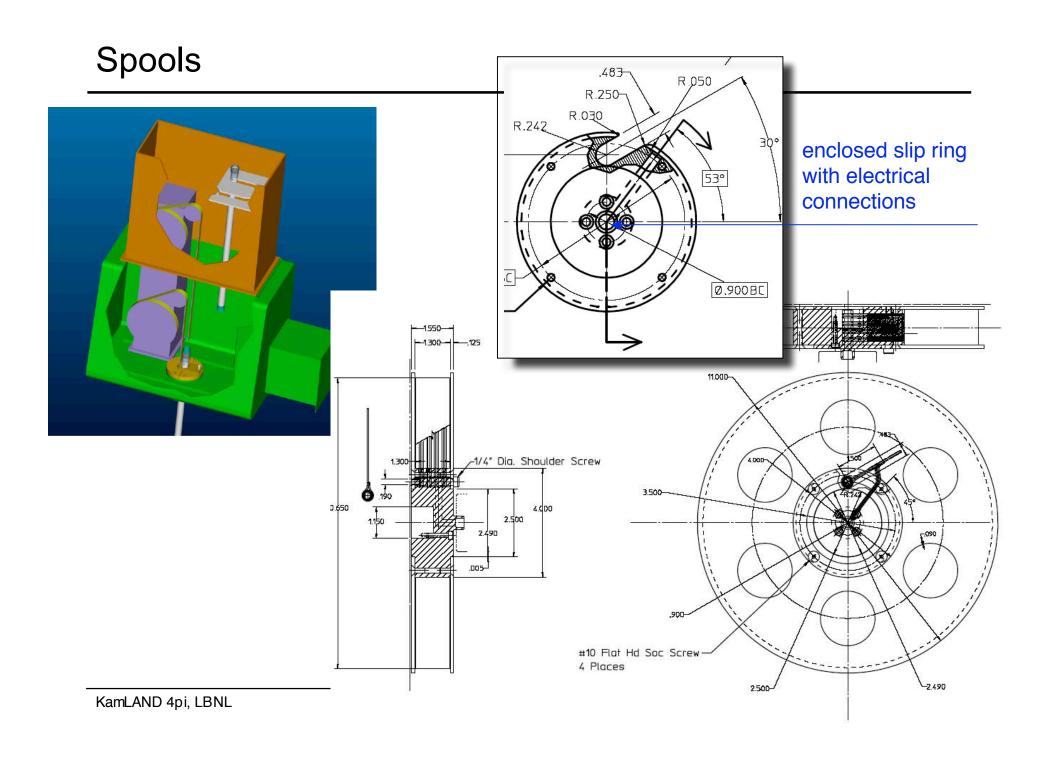


Motor Drive System

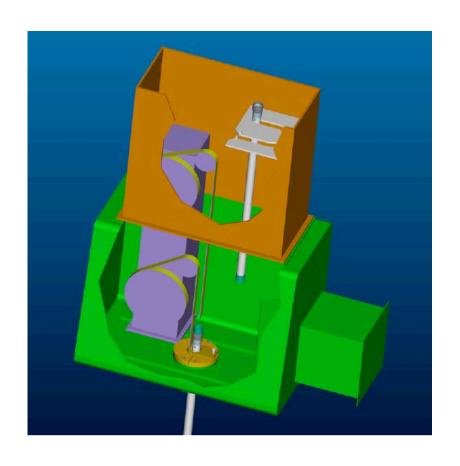




KamLAND 4pi, LBNL



Glovebox System and Deployment Hardware



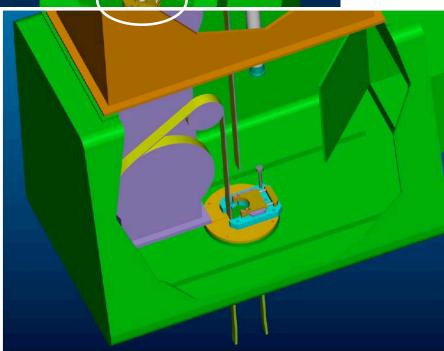


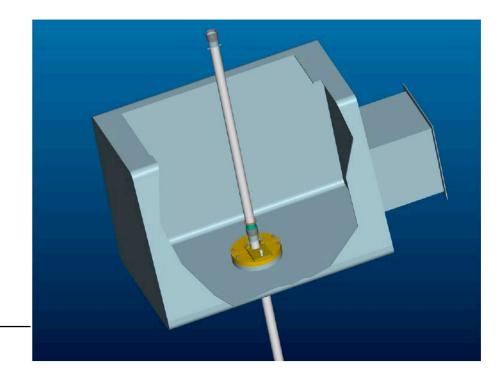
Safety Pin Block



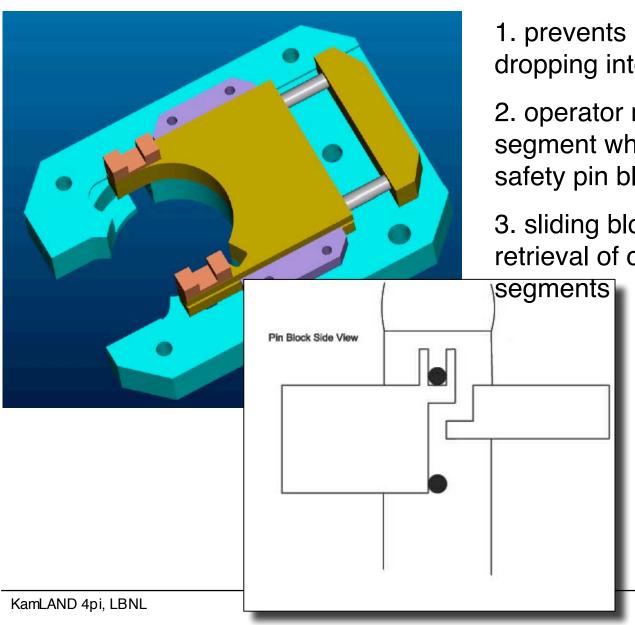
Purpose

- I. Safety block between glovebox and detector.
- II. Used for assembly of pole.
- III. Allows easy retrieval of pole.



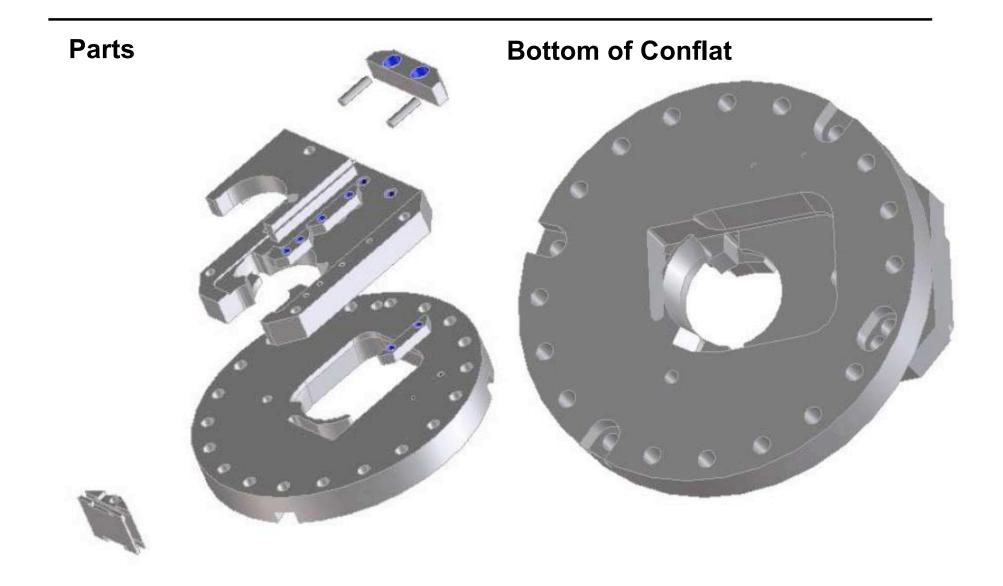


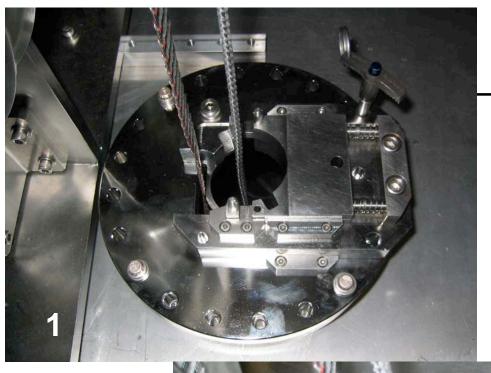
Safety Pin Block



- 1. prevents pole segments from dropping into detector
- 2. operator needs to turn pole segment when engaged in safety pin block
- 3. sliding block allows easy retrieval of calibration pole

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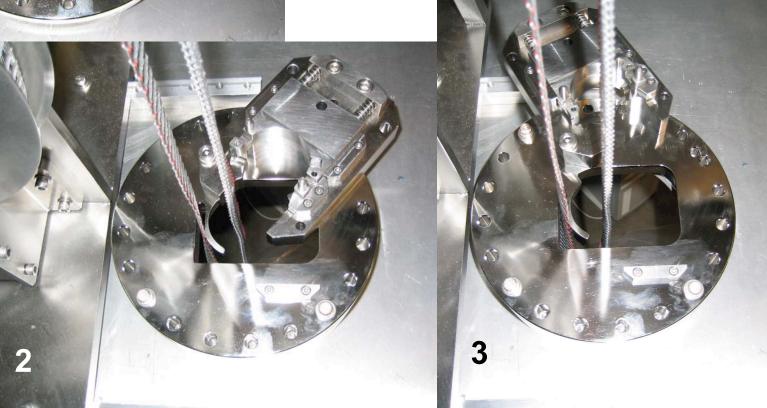




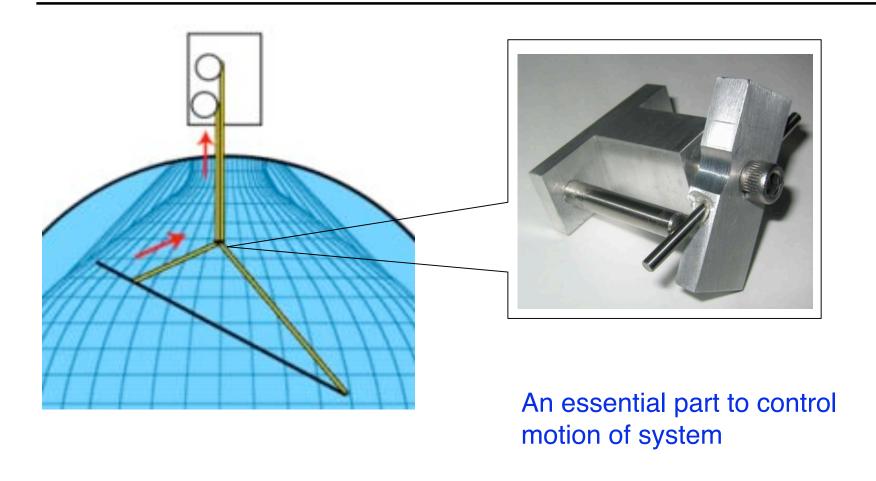
KamLAND 4pi, LBI

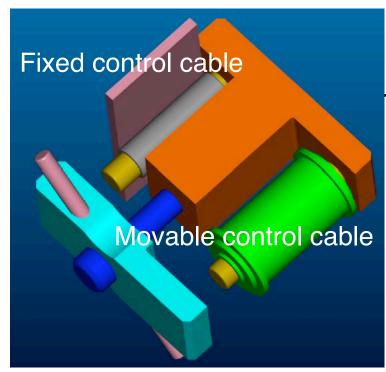
The New Pin Block

- mounted on conflat flange
- guides control cables
- rotates to allow pivot block to pass
- provides 3-step safety lock

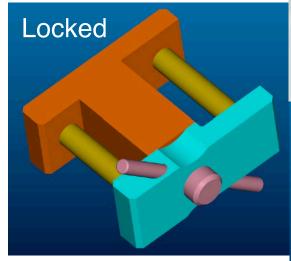


Pivot Block





Pivot Block - Functionality

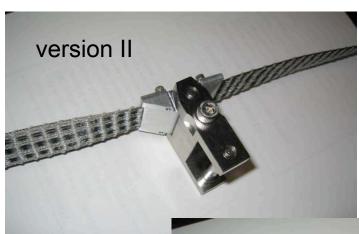




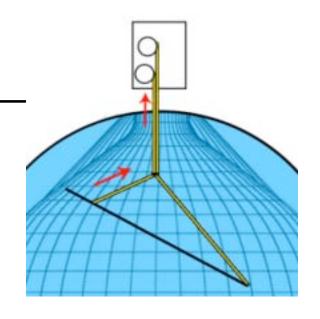
Disengaged

Pivot Block - Revisited

- consists of (1) pivot and (2) clamp
- uses cable clamp, no crimping
- adjustable positioning



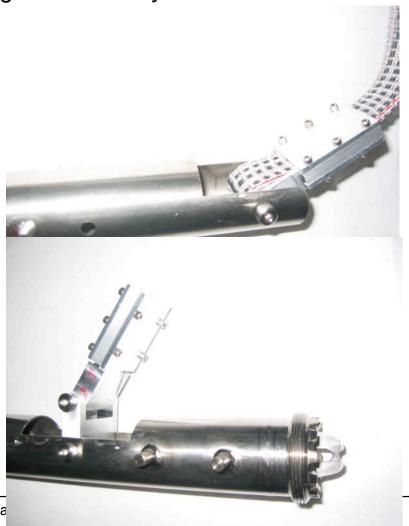


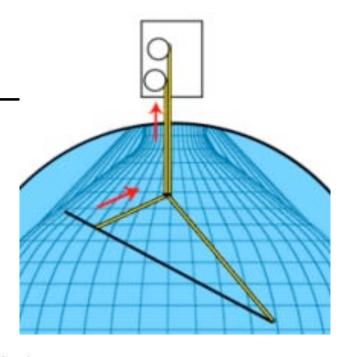


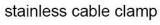


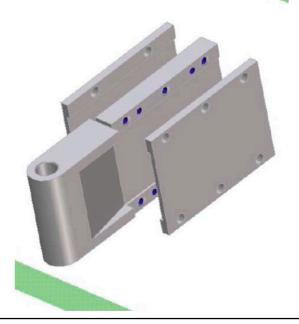
Cable Attachment

- modular
- allows easy replacement of cable
- greater stability and control

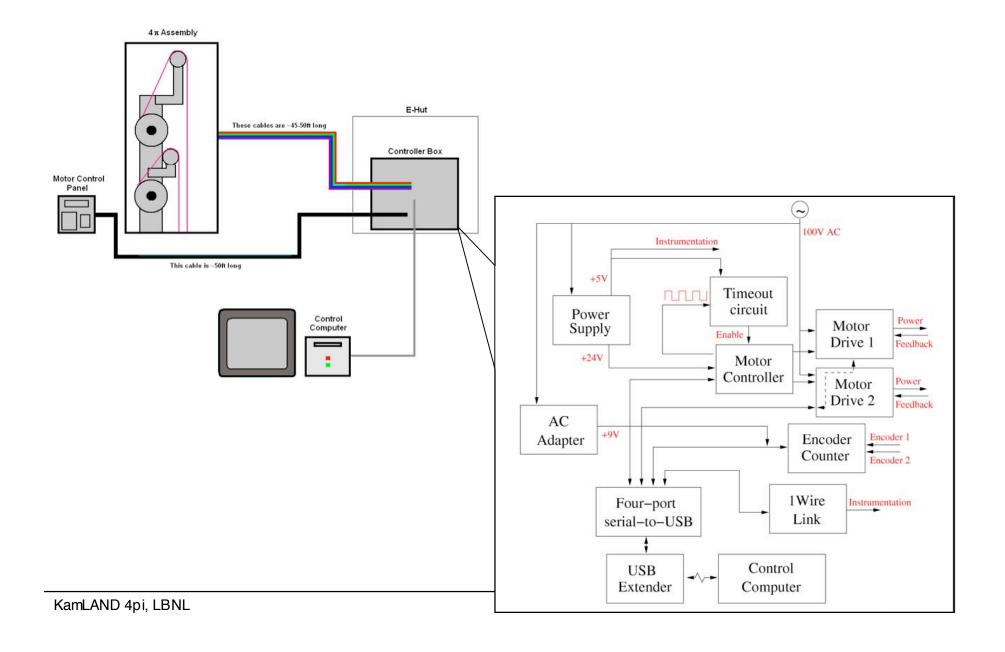




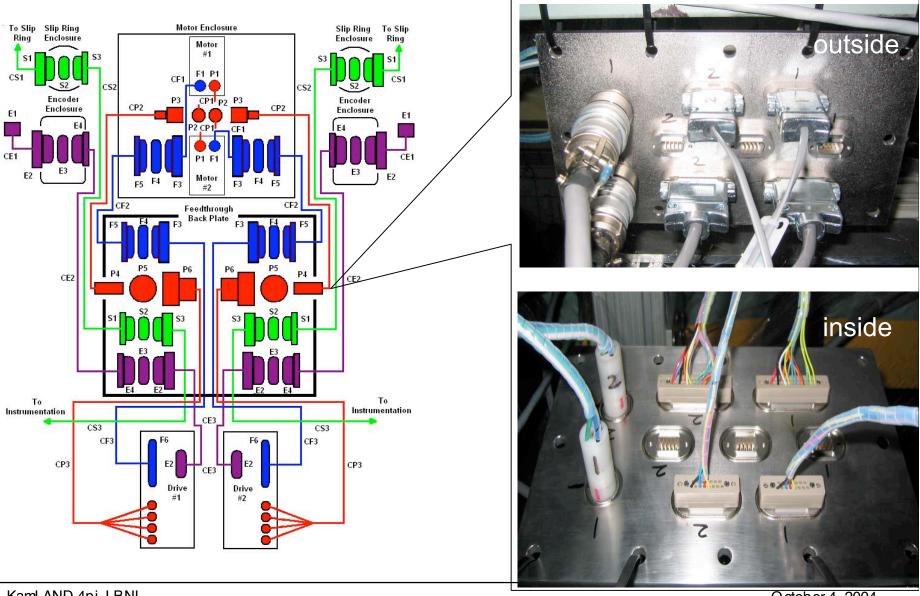




Electrical Cabling and Controls Systems



Electrical Cabling and Glovebox Feedthroughs

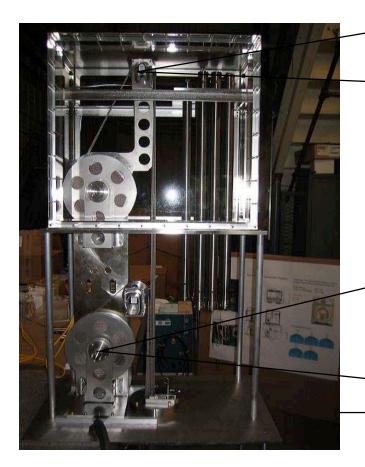


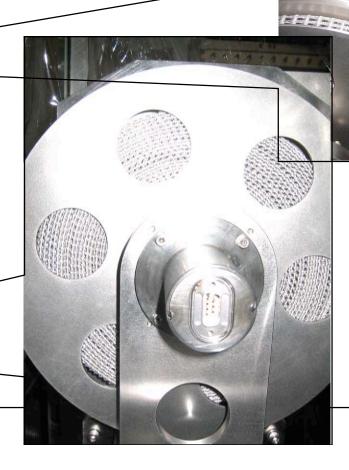
KamLAND 4pi, LBNL

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In-Glovebox Feedthroughs

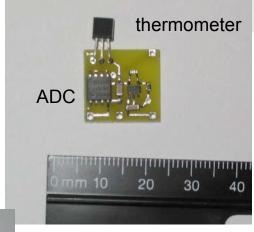
Pulley encoders and slip rings completely encapsulated





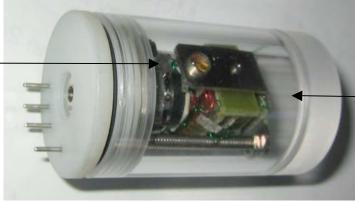
Instrumentation Unit

- prototype completely assembled, being tested
- uses total of 3 wires in control cable
- 4 functions: 1. reads out pressure sensor
 - 2. controls LEDs
 - 3. measures temperature
 - 4. Inclinometer and accelerometer



pressure sensor

830 nm LED



Pressure sensor

Thermometer ADC Interface

 $\label{lem:http://www.maxim-ic.com/quick_view2.cfm?qv_pk=2812&ln=http://www.maxim-ic.com/quick_view2.cfm?qv_pk=2921&ln=http://www.maxim-ic.cfm?qv_pk=2921&ln=http://www.maxim-ic.cfm?qv_pk=2921&ln=http://www.ma$

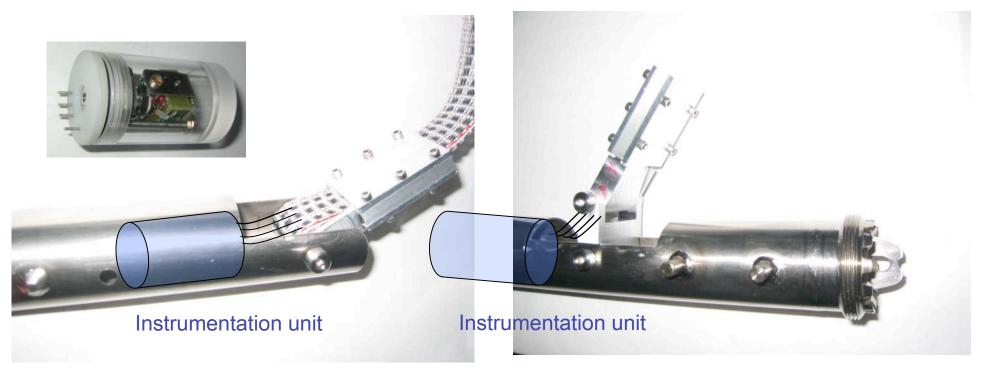
http://www.ibuttonlink.com/Link_Details.htm

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Electrical Connections and Breakout at Cable Ends

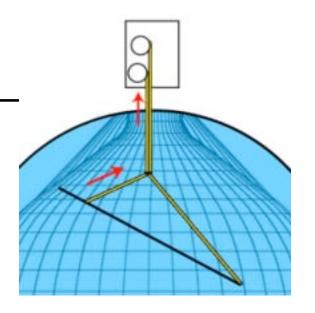
Top Cable End

Lower Cable End



Electrical Connections at the Pivot Block





Planned Improvements and Remaining Technical Work

- Some Examples -

Photoelectric Relay - Home Position Sensor

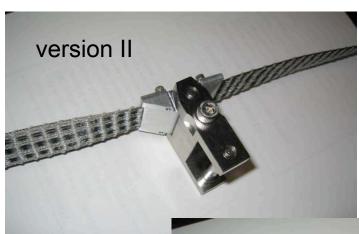
photoelectric IR sensor:

- stops system in home position
- calibrates position encoder

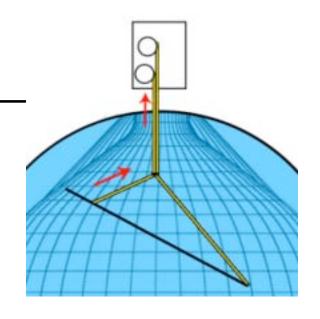


Pivot Block - Revisited

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- adjustable positioning







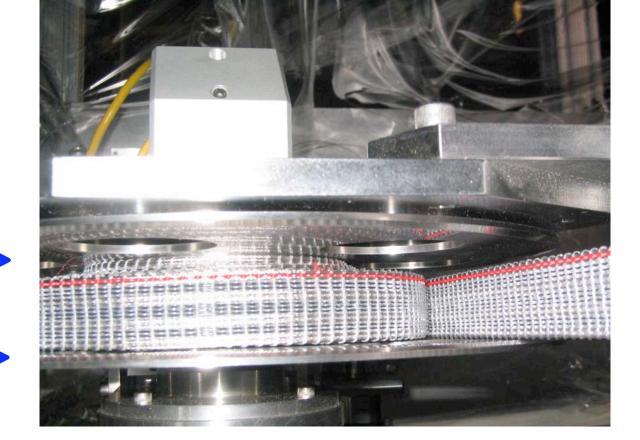


Spools

Needs:

- teflon or stainless spacers on both side of cable to fill spool gap and help guide cable

Quantity: 2 spools

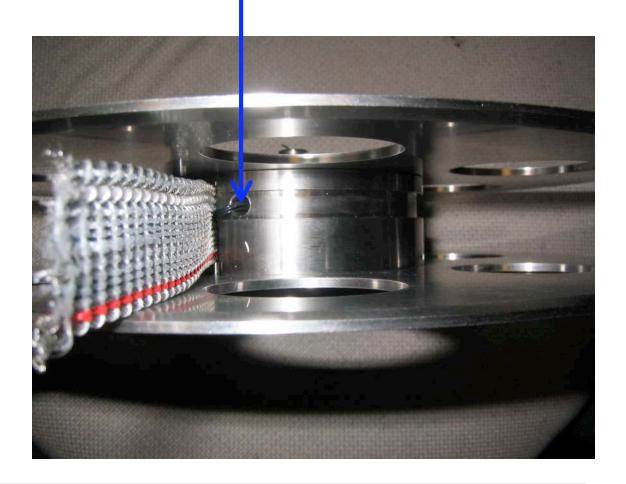


Spools

Needs:

- teflon seal plug for cable connections

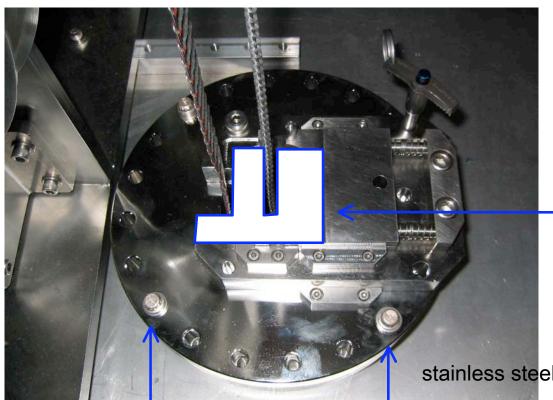
Quantity: 2



Pin Block

Needs:

- removable teflon cable guide
- stainless steel screws with "handle"(to be tightened with gloves)



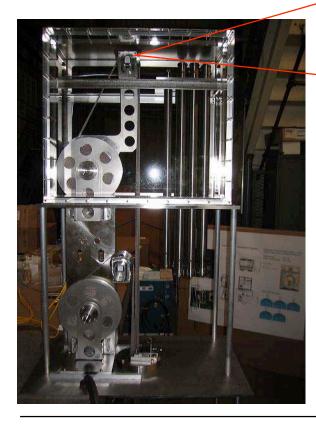
removable teflon cable guide

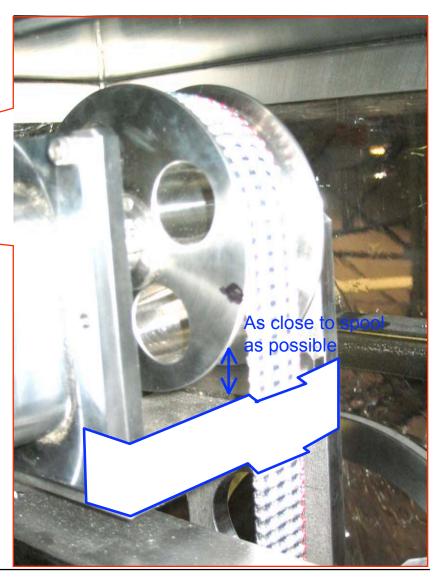
stainless steel screws with "handle"

(to be tightened with gloves)

Needs:

- teflon cable guide for pulley



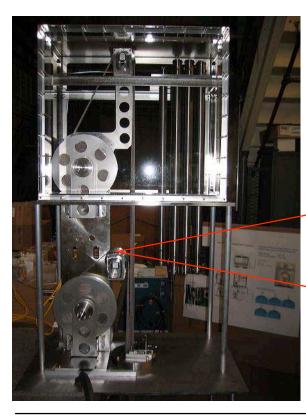


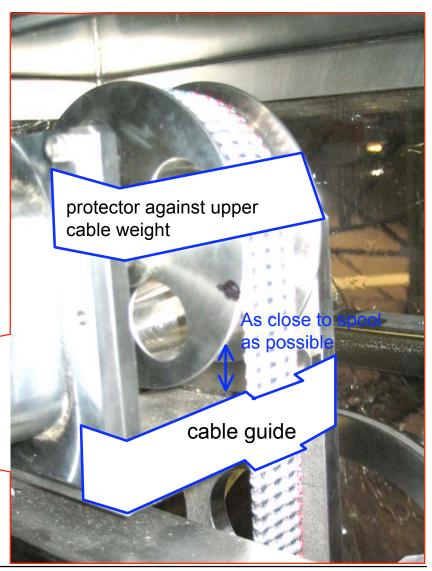
Encoder and Guide Pulleys

Lower Pulley

Needs:

- teflon protector against upper cable weight
- teflon cable guide for pulley





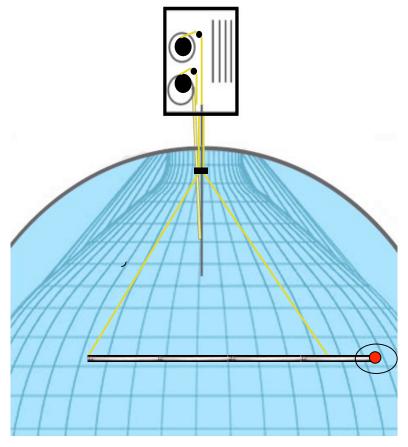
Cable Weight

Needs:

- sliding cable weight
- option to vary mass?

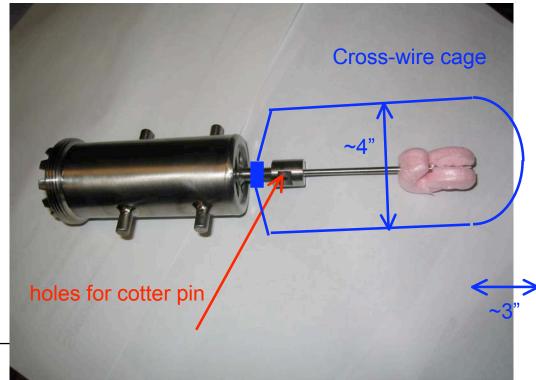
Quantity: 1





Needs:

- 2 stainless-steel cross wires as cage around source. wire cage attaches to source holder.
- make holes fit for cotter pin



Suggestions and Comments

Brian: • May not want to place 4pi control electronics in ehut, will cause noise.

→ Kengo, Karsten will look into placing controls on clean area. May need enclosure for control electronics rack. Also will need longer cables.

What about slip clutch? Are we confident to use software interlock?

Marc: • Do we need drip pan in the glovebox?

Evgueni: • What about PPO residue when oil from cable evaporates in glovebox?

 Instead of slip clutch, can you integrate load sensor to create interlock for cable when it gets caught?

Marc/John: • Can you use exposed connectors for instrumentation unit in scintillator?

What is conductivity of scintillator?

